

PATENT COOPERATION TREATY

PCT

NOTIFICATION OF ELECTION

(PCT Rule 61.2)

From the INTERNATIONAL BUREAU

To:

Assistant Commissioner for Patents
United States Patent and Trademark
Office
Box PCT
Washington, D.C.20231
ETATS-UNIS D'AMERIQUE

in its capacity as elected Office

Date of mailing (day/month/year)

25 September 2000 (25.09.00)

International application No.

PCT/SE99/02255

Applicant's or agent's file reference

103371901

International filing date (day/month/year)

02 December 1999 (02.12.99)

Priority date (day/month/year)

03 December 1998 (03.12.98)

Applicant

PERSSON, Fredrik et al

1. The designated Office is hereby notified of its election made:



in the demand filed with the International Preliminary Examining Authority on:

30 June 2000 (30.06.00)



in a notice effecting later election filed with the International Bureau on:

2. The election ☒ was



was not

made before the expiration of 19 months from the priority date or, where Rule 32 applies, within the time limit under Rule 32.2(b).

The International Bureau of WIPO
34, chemin des Colombettes
1211 Geneva 20, Switzerland

Facsimile No.: (41-22) 740.14.35

Authorized officer

Manu Berrod

Telephone No.: (41-22) 338.83.38

REC'D 23 MAR 2001

WIPO PCT

INTERNATIONAL PRELIMINARY EXAMINATION REPORT

(PCT Article 36 and Rule 70)

14

Applicant's or agent's file reference 103371901	FOR FURTHER ACTION See Notification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416)	
International application No. PCT/SE99/02255	International filing date (day/month/year) 02-12-1999	Priority date (day/month/year) 03-12-1998
International Patent Classification (IPC) or national classification and IPC ₇ B25J 17/02, F16C 11/06		
Applicant ABB AB et al		

1. This international preliminary examination report has been prepared by this International Preliminary Examining Authority and is transmitted to the applicant according to Article 36.

2. This REPORT consists of a total of 3 sheets, including this cover sheet.

☒ This report is also accompanied by ANNEXES, i.e., sheets of the description, claims and/or drawings which have been amended and are the basis for this report and/or sheets containing rectifications made before this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions under the PCT).

These annexes consist of a total of 2 sheets.

3. This report contains indications relating to the following items:

- I ☒ Basis of the report
- II ☐ Priority
- III ☐ Non-establishment of opinion with regard to novelty, inventive step and industrial applicability
- IV ☐ Lack of unity of invention
- V ☒ Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement
- VI ☐ Certain documents cited
- VII ☐ Certain defects in the international application
- VIII ☐ Certain observations on the international application

Date of submission of the demand 30-06-2000	Date of completion of this report 05-03-2001
Name and mailing address of the IPEA/SE Patent- och registreringsverket Box 5055 S-102 42 STOCKHOLM Facsimile No. 08-667 72 88	Authorized officer Ender Dag /itw Telephone No. 08-782 25 00

I. Basis of the report**1. With regard to the elements of the international application:***

- ☐ the international application as originally filed
- ☒ the description:
pages 1-3, as originally filed
pages _____, filed with the demand
pages _____, filed with the letter of _____
- ☒ the claims:
pages _____, as originally filed
pages _____, as amended (together with any statement) under article 19
pages _____, filed with the demand
pages 1-2, filed with the letter of 2000-12-13
- ☒ the drawings:
pages 1-5, as originally filed
pages _____, filed with the demand
pages _____, filed with the letter of _____
- ☐ the sequence listing part of the description:
pages _____, as originally filed
pages _____, filed with the demand
pages _____, filed with the letter of _____

2. With regard to the language, all the elements marked above were available or furnished to this Authority in the language in which the international application was filed, unless otherwise indicated under this item.

These elements were available or furnished to this Authority in the following language ENGLISH which is:

- ☐ the language of a translation furnished for the purposes of international search (under Rule 23.1(b)).
- ☒ the language of publication of the international application (under Rule 48.3(b)).
- ☐ the language of the translation furnished for the purposes of international preliminary examination (under Rules 55.2 and/or 55.3).

3. With regard to any nucleotide and/or amino acid sequence disclosed in the international application, the international preliminary examination was carried out on the basis of the sequence listing:

- ☐ contained in the international application in written form.
- ☐ filed together with the international application in computer readable form.
- ☐ furnished subsequently to this Authority in written form.
- ☐ furnished subsequently to this Authority in computer readable form.
- ☐ The statement that the subsequently furnished written sequence listing does not go beyond the disclosure in the international application as filed has been furnished.
- ☐ The statement that the information recorded in computer readable form is identical to the written sequence listing has been furnished.

4. ☐ The amendments have resulted in the cancellation of:

- ☐ the description, pages _____
- ☐ the claims, Nos. _____
- ☐ the drawings, sheet/fig _____

5. ☐ This report has been established as if (some of) the amendments had not been made, since they have been considered to go beyond the disclosure as filed, as indicated in the Supplemental Box (Rule 70.2 (c)).**

* Replacement sheets which have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are annexed to this report since they do not contain amendments (Rules 70.16 and 70.17).

** Any replacement sheet containing such amendments must be referred to under item 1 and annexed to this report.

INTERNATIONAL PRELIMINARY EXAMINATION REPORT

International application No.

PCT/SE99/02255

V. Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

1. Statement

Novelty (N)	Claims	<u>1-11</u>	YES
	Claims		NO
Inventive step (IS)	Claims	<u>1-11</u>	YES
	Claims		NO
Industrial applicability (IA)	Claims	<u>1-11</u>	YES
	Claims		NO

2. Citations and explanations (Rule 70.7)

The invention relates to a robot including a device for eliminating play in a three axle-joint. According to the invention the device comprises an annular bearing fixed tightly in a housing in the joint socket. The housing has a grooved surface designed to increase friction on the abutting bearing by permanent deformation of the bearing.

Documents cited in the International Search Report

D1: US 4 976 582 A
D2: US 4 695 182 A
D3: EP 0 705 990 A2

Document D1 discloses a device for movement and positioning of an element in space. The device includes end of control arms integrated by ball-and-socket joints.

Document D2 discloses a ball and socket joint with mechanical interlock.

Document D3 discloses a spherical joint with a bushing between an inner- and outer member.

The invention according to claims 1-11 differs from what is known in D1, D2 and D3 by the housing in the joint socket having a grooved surface designed to increase friction on the abutting bearing. The teaching of the prior art as disclosed in the cited documents does not lead a skilled person to the invention. Therefore, the invention defined in the claims is not obvious to a person skilled in the art.

The invention according to claims 1-11 is thus novel and is considered to involve an inventive step. The invention also has industrial applicability.

PATENT COOPERATION TREATY

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INTERNATIONAL SEARCH REPORT

(PCT Article 18 and Rules 43 and 44)

Applicant's or agent's file reference 103371901	FOR FURTHER ACTION	see Notification of Transmittal of International Search Report (Form PCT/ISA/220) as well as, where applicable, item 5 below.
International application No. PCT/SE 99/02255	International filing date (day/month/year) 2 December 1999	(Earliest) Priority Date (day/month/year) 3 December 1998
Applicant ABB AB et al		

This international search report has been prepared by this International Searching Authority and is transmitted to the applicant according to Article 18. A copy is being transmitted to the International Bureau.

This international search report consists of a total of 3 sheets.

☒ It is also accompanied by a copy of each prior art document cited in this report.

1. ☐ Certain claims were found unsearchable (See Box I).

2. ☐ Unity of invention is lacking (See Box II).

3. ☐ The international application contains disclosure of a nucleotide and/or amino acid sequence listing and the international search was carried out on the basis of the sequence listing

☐

filed with the international application.

☐

furnished by the applicant separately from the international application,

☐

but not accompanied by a statement to the effect that it did not include matter going beyond the disclosure in the international application as filed.

☐

transcribed by this Authority.

4. With regard to the title, ☒ the text is approved as submitted by the applicant.

☐

the text has been established by this Authority to read as follows:

5. With regard to the abstract,

☒

the text is approved as submitted by the applicant.

☐

the text has been established, according to Rule 38.2(b), by this Authority as it appears in Box III. The applicant may, within one month from the date of mailing of this international search report, submit comments to this Authority.

6. The figure of the drawings to be published with the abstract is:

Figure No. 1

☒

as suggested by the applicant.

☐

because the applicant failed to suggest a figure.

☐

because this figure better characterizes the invention.

☐

None of the figures.

INTERNATIONAL SEARCH REPORT

International application No.
PCT/SE 99/02255

A. CLASSIFICATION OF SUBJECT MATTER

IPC7: B25J 17/02, F16C 11/06

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC7: B25J, F16C

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

SE,DK,FI,NO classes as above

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim: No.
Y	US 4976582 A (CLAVEL), 11 December 1990 (11.12.90), figures --	1-12
Y	US 4695182 A (WOOD, JR.), 22 Sept 1987 (22.09.87), column 5, line 64 - column 6, line 3 --	1-12
Y	EP 0705990 A2 (THK CO. LTD.), 10 April 1996 (10.04.96), column 9, line 44 - line 55 --	1,3-4,9-11
A	US 3856423 A (UCHIDA), 24 December 1974 (24.12.74), column 3, line 66 - column 4, line 6; column 1, line 56 - line 57 --	1,5,7,11

☒ Further documents are listed in the continuation of Box C.

☒ See patent family annex.

* Special categories of cited documents:

- "A" document defining the general state of the art which is not considered to be of particular relevance
- "B" earlier document but published on or after the international filing date
- "I" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance: the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

15 February 2000

Date of mailing of the international search report

17 -04- 2000

Name and mailing address of the ISA
Swedish Patent Office
Box 5055, S-102 42 STOCKHOLM
Facsimile No. +46 8 666 02 86

Authorized officer
Christer Jön / MR
Telephone No. +46 8 782 25 00

INTERNATIONAL SEARCH REPORT

International application No.
PCT/SE 99/02255

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 4203683 A (ROGERS), 20 May 1980 (20.05.80), column 2, line 56 - line 61 -- -----	1

INTERNATIONAL SEARCH REPORT
Information on patent family members

02/12/99

International application No.
PCT/SE 99/02255

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 4976582 A	11/12/90	AT 65200 T CA 1298806 A CH 672089 A,B EP 0250470 A,B SE 0250470 T3 JP 4045310 B JP 63501860 T WO 8703528 A	15/08/91 14/04/92 31/10/89 07/01/88 24/07/92 28/07/88 18/06/87
US 4695182 A	22/09/87	DE 3720137 A,C JP 2599137 B JP 62297527 A DE 3700057 A,C JP 1954745 C JP 6070442 B JP 62184217 A US 4712940 A	23/12/87 09/04/97 24/12/87 16/07/87 28/07/95 07/09/94 12/08/87 15/12/87
EP 0705990 A2	10/04/96	EP 0955480 A JP 8152018 A US 5653547 A	10/11/99 11/06/96 05/08/97
US 3856423 A	24/12/74	AU 475212 B AU 6524774 A BR 7400814 D CA 1007474 A DE 2326018 A,C FR 2216853 A GB 1447258 A IT 1007548 B JP 964830 C JP 49101762 A JP 53044620 B	12/08/76 07/08/75 00/00/00 29/03/77 22/08/74 30/08/74 25/08/76 30/10/76 20/07/79 26/09/74 30/11/78
US 4203683 A	20/05/80	AU 517401 B AU 3498178 A BR 7802204 A CA 1079533 A DE 2814234 A FR 2387375 A GB 1597495 A IT 1108019 B JP 53126465 A TR 20701 A	30/07/81 18/10/79 05/12/78 17/06/80 26/10/78 10/11/78 09/09/81 02/12/85 04/11/78 11/05/82

RECORD COPY

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REQUEST

The undersigned requests that the present international application be processed according to the Patent Cooperation Treaty.

For receiving Office use only

International Application No.

PCT/SE 99 / 0 2 2 5 5

International Filing Date

02 -12- 1999

The Swedish Patent Office
PCT International Application

Name of receiving Office and "PCT International Application"

Applicant's or agent's file reference

(if desired) (12 characters maximum)

103371901

Box No. I TITLE OF INVENTION	
Robot Device	
Box No. II APPLICANT	
Name and address: (Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (that is, country) of residence if no state of residence is indicated below.) <div style="text-align: center;">ABB AB</div> <div style="text-align: center;">SE-721 83 VÄSTERÅS</div> <div style="text-align: center;">Sweden</div>	<input type="checkbox"/> This person is also inventor. Telephone No. Facsimile No. Teleprinter No.
State (that is, country) of nationality: <div style="text-align: center;">Sweden</div>	State (that is, country) of residence: <div style="text-align: center;">Sweden</div>
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input checked="" type="checkbox"/> all designated States except the United States of America <input type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box	
Box No. III FURTHER APPLICANT(S) AND/OR (FURTHER) INVENTOR(S)	
Name and address: (Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (that is, country) of residence if no state of residence is indicated below.) <div style="text-align: center;">PERSSON Fredrik</div> <div style="text-align: center;">Markörgatan 10 A</div> <div style="text-align: center;">SE-723 38 VÄSTERÅS</div> <div style="text-align: center;">Sweden</div>	This person is: <input type="checkbox"/> applicant only <input checked="" type="checkbox"/> applicant and inventor <input type="checkbox"/> inventor only (If this check-box is marked, do not fill in below.)
State (that is, country) of nationality: <div style="text-align: center;">Sweden</div>	State (that is, country) of residence: <div style="text-align: center;">Sweden</div>
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input type="checkbox"/> all designated States except the United States of America <input checked="" type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box	
<input checked="" type="checkbox"/> Further applicants and/or (further) inventors are indicated on a continuation sheet.	
Box No. IV AGENT OR COMMON REPRESENTATIVE; OR ADDRESS FOR CORRESPONDENCE	
The person identified below is hereby/has been appointed to act on behalf of the applicant(s) before the competent International Authorities as: <input checked="" type="checkbox"/> agent <input type="checkbox"/> common representative	
Name and address: (Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country.) <div style="text-align: center;">Urban Petr�</div> <div style="text-align: center;">AB STOCKHOLMS PATENTBYR� , Zacco & Bruhn</div> <div style="text-align: center;">Box 23101, SE-104 35 STOCKHOLM, Sweden</div>	Telephone No. <div style="text-align: center;">+46 8 729 95 00</div> Facsimile No. <div style="text-align: center;">+46 8 31 83 15</div> Teleprinter No.
<input type="checkbox"/> Address for correspondence: Mark this check-box where no agent or common representative is/has been appointed and the space above is used instead to indicate a special address to which correspondence should be sent.	

Continuation of Box No. III		FURTHER APPLICANTS AND/OR (FURTHER) INVENTORS	
<i>If none of the following sub-boxes is used, this sheet is not to be included in the request.</i>			
Name and address: <i>(Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (i.e. country) of residence if no state of residence is indicated below.)</i> MIKAELSSON Pierre Haga Parkgatan 3 D SE-723 36 VÄSTERÅS Sweden		This person is: <input type="checkbox"/> applicant only <input checked="" type="checkbox"/> applicant and inventor <input type="checkbox"/> inventor only <i>(If this check-box is marked, do not fill in below.)</i>	
State (i.e. country) of nationality: Sweden	State (i.e. country) of residence: Sweden		
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input type="checkbox"/> all designated States except the United States of America <input checked="" type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box			
Name and address: <i>(Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (i.e. country) of residence if no state of residence is indicated below.)</i> HVITTFELDT Håkan Brunnbygatan 64 SE-722 23 VÄSTERÅS Sweden		This person is: <input type="checkbox"/> applicant only <input checked="" type="checkbox"/> applicant and inventor <input type="checkbox"/> inventor only <i>(If this check-box is marked, do not fill in below.)</i>	
State (i.e. country) of nationality: Sweden	State (i.e. country) of residence: Sweden		
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input type="checkbox"/> all designated States except the United States of America <input checked="" type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box			
Name and address: <i>(Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (i.e. country) of residence if no state of residence is indicated below.)</i> LARSSON Jan Adolf Zethelius gata 11 SE-724 78 VÄSTERÅS Sweden		This person is: <input type="checkbox"/> applicant only <input checked="" type="checkbox"/> applicant and inventor <input type="checkbox"/> inventor only <i>(If this check-box is marked, do not fill in below.)</i>	
State (i.e. country) of nationality: Sweden	State (i.e. country) of residence: Sweden		
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input type="checkbox"/> all designated States except the United States of America <input checked="" type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box			
Name and address: <i>(Family name followed by given name; for a legal entity, full official designation. The address must include postal code and name of country. The country of the address indicated in this Box is the applicant's State (i.e. country) of residence if no state of residence is indicated below.)</i> 		This person is: <input type="checkbox"/> applicant only <input type="checkbox"/> applicant and inventor <input type="checkbox"/> inventor only <i>(If this check-box is marked, do not fill in below.)</i>	
State (i.e. country) of nationality:	State (i.e. country) of residence:		
This person is applicant for the purposes of: <input type="checkbox"/> all designated States <input type="checkbox"/> all designated States except the United States of America <input type="checkbox"/> the United States of America only <input type="checkbox"/> the States indicated in the Supplemental Box			
<input type="checkbox"/> Further applicants and/or (further) inventors are indicated on another continuation sheet.			

Box No.V DESIGNATION OF STATES

The following designations are hereby made under Rule 4.9(a) (mark the applicable check-boxes; at least one must be marked):

Regional Patent

- ☒ AP ARIPO Patent: GH Ghana, GM Gambia, KE Kenya, LS Lesotho, MW Malawi, SD Sudan, SL Sierra Leone, SZ Swaziland, UG Uganda, ZW Zimbabwe, and any other State which is a Contracting State of the Harare Protocol and of the PCT
- ☒ EA Eurasian Patent: AM Armenia, AZ Azerbaijan, BY Belarus, KG Kyrgyzstan, KZ Kazakhstan, MD Republic of Moldova, RU Russian Federation, TJ Tajikistan, TM Turkmenistan, and any other State which is a Contracting State of the Eurasian Patent Convention and of the PCT
- ☒ EP European Patent: AT Austria, BE Belgium, CH and LI Switzerland and Liechtenstein, CY Cyprus, DE Germany, DK Denmark, ES Spain, FI Finland, FR France, GB United Kingdom, GR Greece, IE Ireland, IT Italy, LU Luxembourg, MC Monaco, NL Netherlands, PT Portugal, SE Sweden, and any other State which is a Contracting State of the European Patent Convention and of the PCT
- ☒ OA OAPI Patent: BF Burkina Faso, BJ Benin, CF Central African Republic, CG Congo, CI Côte d'Ivoire, CM Cameroon, GA Gabon, GN Guinea, GW Guinea-Bissau, ML Mali, MR Mauritania, NE Niger, SN Senegal, TD Chad, TG Togo, and any other State which is a member State of OAPI and a Contracting State of the FCT (if other kind of protection or treatment desired, specify on dotted line).....

National Patent (if other kind of protection or treatment desired, specify on dotted line):

- | | |
|---|---|
| <input checked="" type="checkbox"/> AE United Arab Emirates..... | <input checked="" type="checkbox"/> LR Liberia..... |
| <input checked="" type="checkbox"/> AL Albania..... | <input checked="" type="checkbox"/> LS Lesotho..... |
| <input checked="" type="checkbox"/> AM Armenia..... | <input checked="" type="checkbox"/> LT Lithuania..... |
| <input checked="" type="checkbox"/> AT Austria..... and utility model. | <input checked="" type="checkbox"/> LU Luxembourg..... |
| <input checked="" type="checkbox"/> AU Australia..... | <input checked="" type="checkbox"/> LV Latvia..... |
| <input checked="" type="checkbox"/> AZ Azerbaijan..... | <input checked="" type="checkbox"/> MA Morocco..... |
| <input checked="" type="checkbox"/> BA Bosnia and Herzegovina..... | <input checked="" type="checkbox"/> MD Republic of Moldova..... |
| <input checked="" type="checkbox"/> BB Barbados..... | <input checked="" type="checkbox"/> MG Madagascar..... |
| <input checked="" type="checkbox"/> BG Bulgaria..... | <input checked="" type="checkbox"/> MK The former Yugoslav Republic of Macedonia..... |
| <input checked="" type="checkbox"/> BR Brazil..... | <input checked="" type="checkbox"/> MN Mongolia..... |
| <input checked="" type="checkbox"/> BY Belarus..... | <input checked="" type="checkbox"/> MW Malawi..... |
| <input checked="" type="checkbox"/> CA Canada..... | <input checked="" type="checkbox"/> MX Mexico..... |
| <input checked="" type="checkbox"/> CH and LI Switzerland and Liechtenstein..... | <input checked="" type="checkbox"/> NO Norway..... |
| <input checked="" type="checkbox"/> CN China..... | <input checked="" type="checkbox"/> NZ New Zealand..... |
| <input checked="" type="checkbox"/> CR Costa Rica..... | <input checked="" type="checkbox"/> PL Poland..... |
| <input checked="" type="checkbox"/> CU Cuba..... | <input checked="" type="checkbox"/> PT Portugal..... |
| <input checked="" type="checkbox"/> CZ Czech Republic..... and utility model | <input checked="" type="checkbox"/> RO Romania..... |
| <input checked="" type="checkbox"/> DE Germany..... and utility model | <input checked="" type="checkbox"/> RU Russian Federation..... |
| <input checked="" type="checkbox"/> DK Denmark..... and utility model | <input checked="" type="checkbox"/> SD Sudan..... |
| <input checked="" type="checkbox"/> DM Dominica..... | <input checked="" type="checkbox"/> SE Sweden..... |
| <input checked="" type="checkbox"/> EE Estonia..... and utility model | <input checked="" type="checkbox"/> SG Singapore..... |
| <input checked="" type="checkbox"/> ES Spain..... | <input checked="" type="checkbox"/> SI Slovenia..... |
| <input checked="" type="checkbox"/> FI Finland..... and utility model | <input checked="" type="checkbox"/> SK Slovakia..... and utility model |
| <input checked="" type="checkbox"/> GB United Kingdom..... | <input checked="" type="checkbox"/> SL Sierra Leone..... |
| <input checked="" type="checkbox"/> GD Grenada..... | <input checked="" type="checkbox"/> TJ Tajikistan..... |
| <input checked="" type="checkbox"/> GE Georgia..... | <input checked="" type="checkbox"/> TM Turkmenistan..... |
| <input checked="" type="checkbox"/> GH Ghana..... | <input checked="" type="checkbox"/> TR Turkey..... |
| <input checked="" type="checkbox"/> GM Gambia..... | <input checked="" type="checkbox"/> TT Trinidad and Tobago..... |
| <input checked="" type="checkbox"/> HR Croatia..... | <input checked="" type="checkbox"/> TZ Tanzania..... |
| <input checked="" type="checkbox"/> HU Hungary..... | <input checked="" type="checkbox"/> UA Ukraine..... |
| <input checked="" type="checkbox"/> ID Indonesia..... | <input checked="" type="checkbox"/> UG Uganda..... |
| <input checked="" type="checkbox"/> IL Israel..... | <input checked="" type="checkbox"/> US United States of America..... |
| <input checked="" type="checkbox"/> IN India..... | <input checked="" type="checkbox"/> UZ Uzbekistan..... |
| <input checked="" type="checkbox"/> IS Iceland..... | <input checked="" type="checkbox"/> VN Viet Nam..... |
| <input checked="" type="checkbox"/> JP Japan..... | <input checked="" type="checkbox"/> YU Yugoslavia..... |
| <input checked="" type="checkbox"/> KE Kenya..... | <input checked="" type="checkbox"/> ZA South Africa..... |
| <input checked="" type="checkbox"/> KG Kyrgyzstan..... | <input checked="" type="checkbox"/> ZW Zimbabwe..... |
| <input checked="" type="checkbox"/> KP Democratic People's Republic of Korea..... | |
| <input checked="" type="checkbox"/> KR Republic of Korea..... | |
| <input checked="" type="checkbox"/> KZ Kazakhstan..... | |
| <input checked="" type="checkbox"/> LC Saint Lucia..... | |
| <input checked="" type="checkbox"/> LK Sri Lanka..... | |

Check-boxes reserved for designating States (for the purposes of a national patent) which have become party to the PCT after Issuance of this sheet:

- ☐
☐

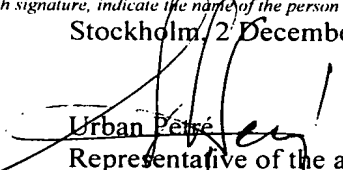
Precautionary Designation Statement: In addition to the designations made above, the applicant also makes under Rule 4.9(b) all other designations which would be permitted under the PCT except any designation(s) indicated in the Supplemental Box as being excluded from the scope of this statement. The applicant declares that those additional designations are subject to confirmation and that any designation which is not confirmed before the expiration of 15 months from the priority date is to be regarded as withdrawn by the applicant at the expiration of that time limit. (Confirmation of a designation consists of the filing of a notice specifying that designation and the payment of the designation and confirmation fees. Confirmation must reach the receiving Office within the 15-month time limit.)

Supplemental box*If the Supplemental Box is not used, this sheet should not be included in the Request.*

1. *If, in any of the Boxes, the space is insufficient to furnish all the information: in such case, write "Continuation of Box No. ..." (indicate the number of the Box) and furnish the information in the same manner as required according to the captions of the Box in which the space was insufficient, in particular.*
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Grip, Joakim
Hansson, Hans-Erik
Hansson, Sven A.
Hinz, Udo
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		national application: country	regional application: * regional Office	international application: receiving Office
item (1) 3/12/98 3 December 1998	9804215-3	SE		
item (2)				
item (3)				
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Figure of the drawings which should accompany the abstract: Fig. 1		Language of filing of the international application: Swedish		
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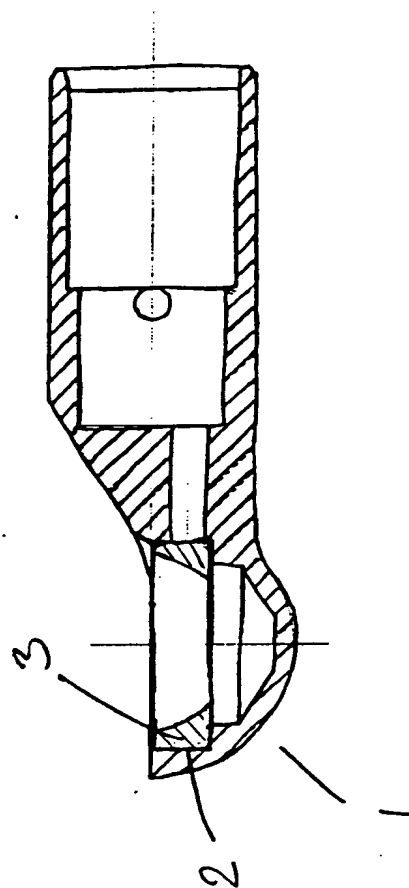


fig 1

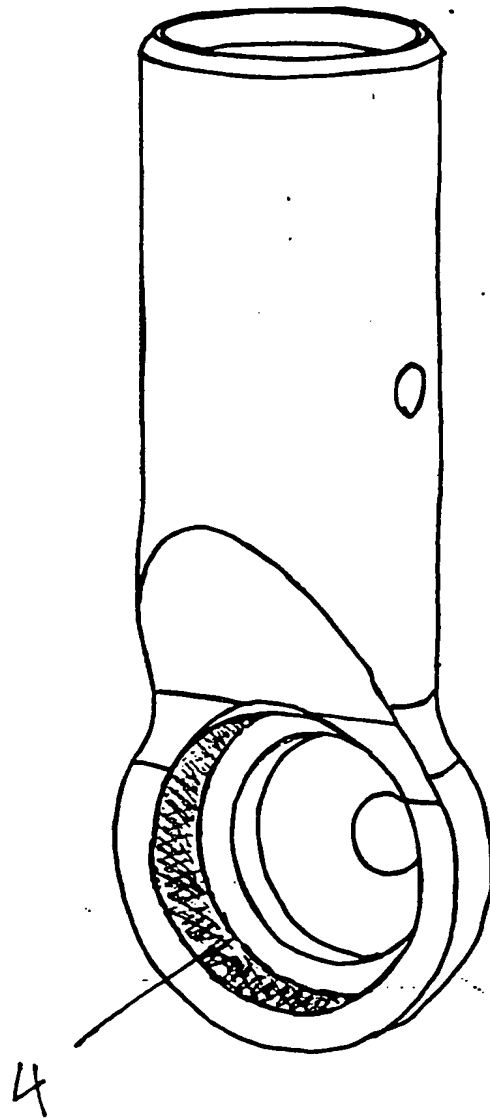


fig 2

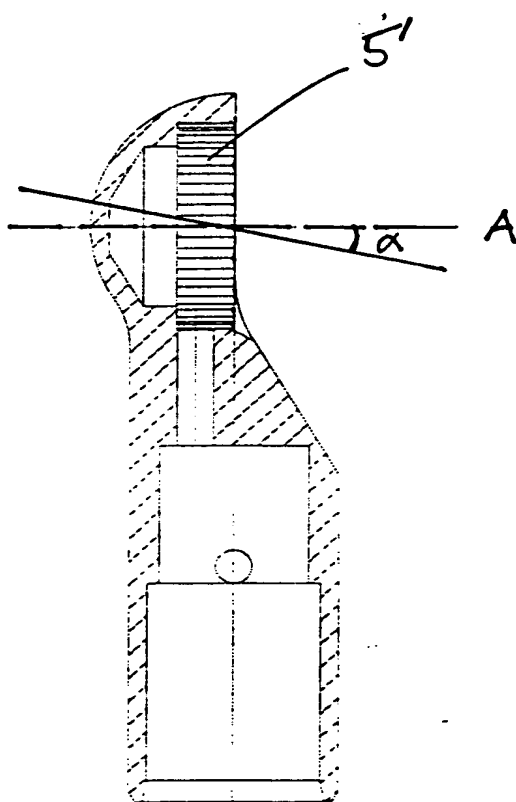


fig 3

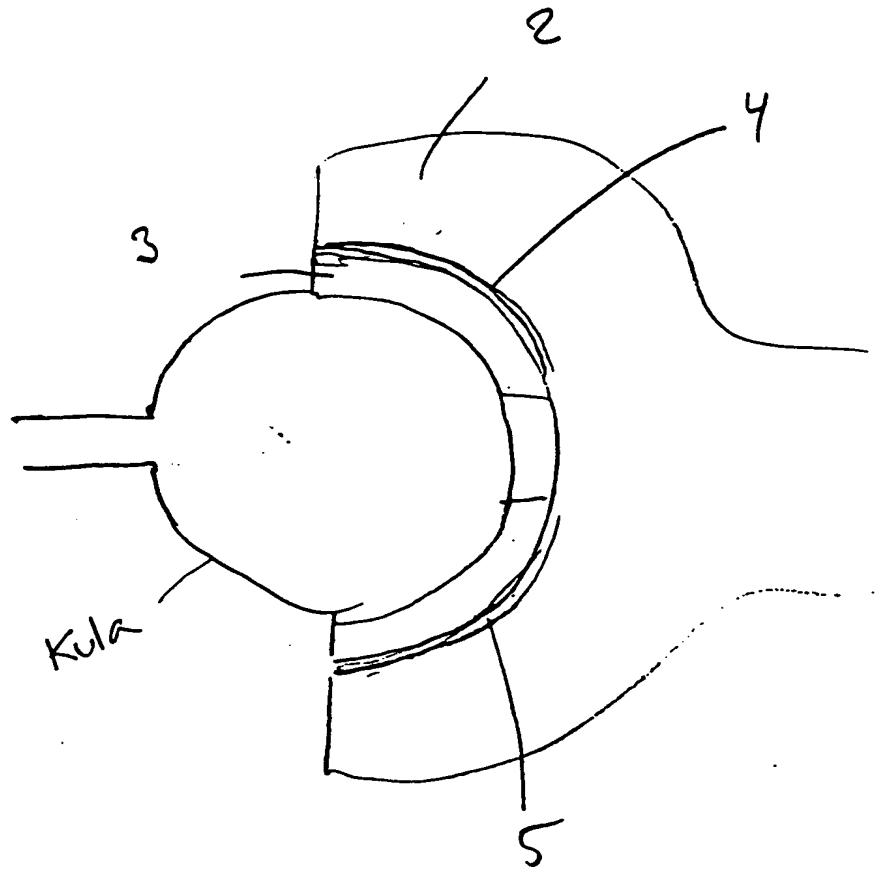
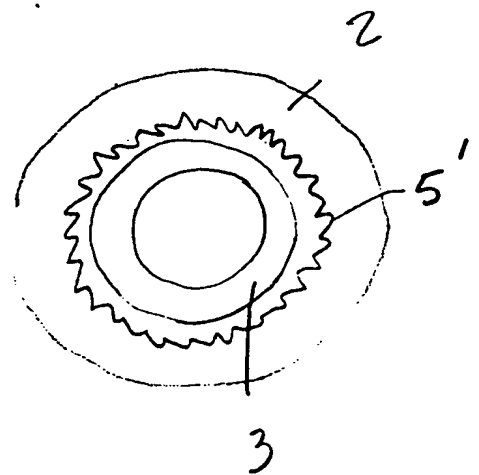


fig 4



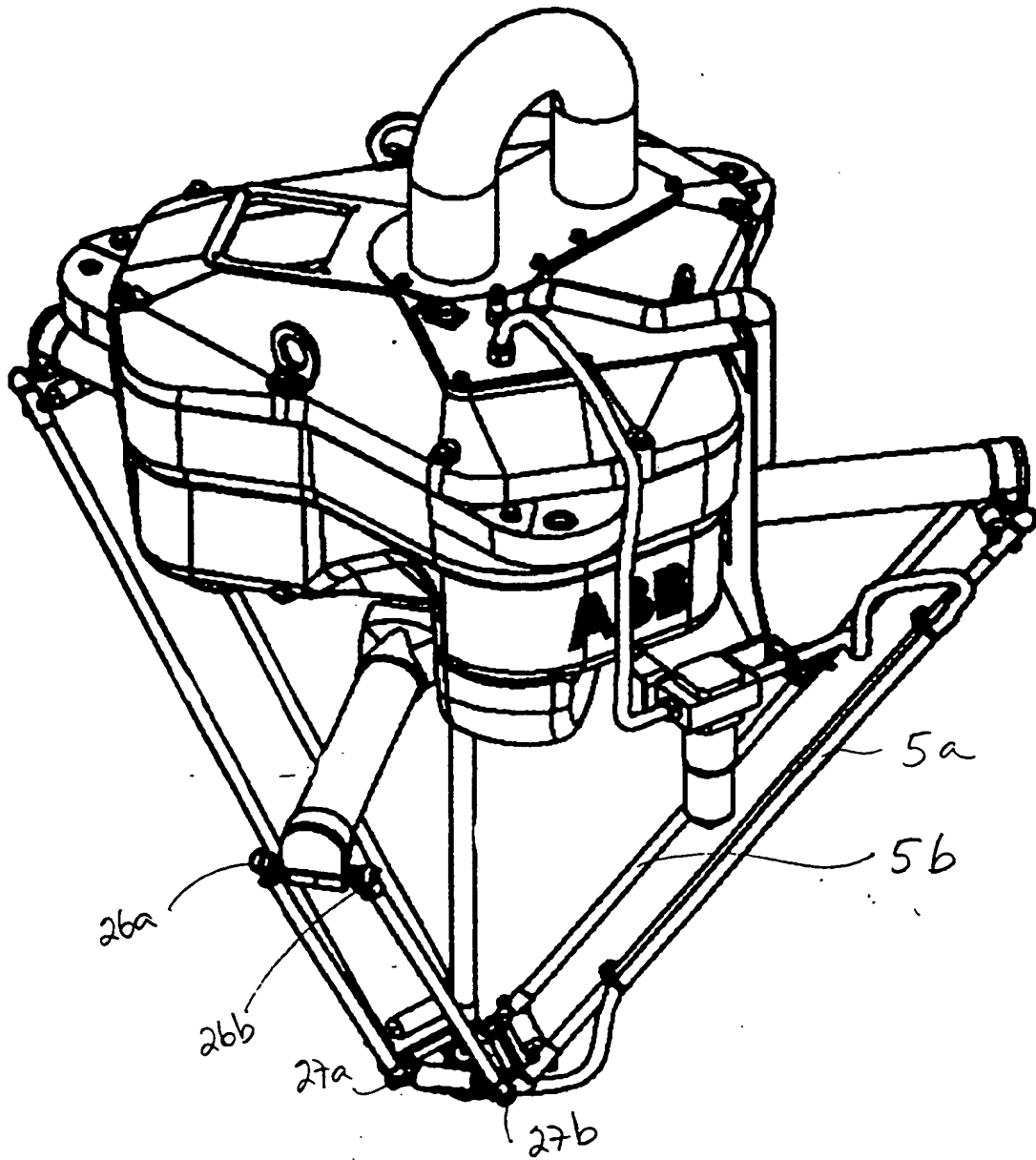


FIG. 5

KN 8565 WO/JS

1999-11-25

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ROBOT DEVICE

10 TEKNISKT OMRÅDE

Föreliggande uppfinning hänför sig till en anordning, användning och ett förfarande för att i en treaxlig led i en robot eliminera risken för glapp.

15

TEKNIKENS STÅNDPUNKT

Vid deltarobotar sker en positionering av ett rörligt element i förhållande till ett fast element (fig 5). Tre drivanordningar driver varsin länkanordning anordnad mellan det fasta och det rörliga elementet. Länkanordningarna kan innefatta stag anordnade i flerledssystem, där lederna kan utgöras av kula-skål-leder.

I den amerikanska patentskriften US,A, 4 976 582 visas bland annat en deltarobot med två parallella länkar 5a och 5b ledat förbundna med kula-skål-leder 26a, 26b, 27a och 27b (fig 5). Ledskålarna är fästade i ändarna på länkarna.

Kula-skål-lederna enligt uppfinningen är utformade med utbytbara lager som minimerar friktionen i leden. Lagret har en skålformad inneryta och är tillverkat av självsmörjande polymermaterial. Lagret är anordnat i ett säte i ledskålen. Under drift av roboten sker dels ledrörelser i kula-skål-lederna och dels rotationsrörelser.

Problem uppstår när lagret följer med rotationsrörelsen dvs följer med ledkulans rotationsrörelse. Härvid sker ledrörelserna vid samma radier hos ledskålen vid varje slag hos länkanordningen, varvid nötning sker upprepade gånger på samma ställen. Ett ojämnt slitage uppstår i leden, vilket förorsakar glapp i leden och därmed ökad friktion i leden. Orsaken till att lagret roterar med ledkulan är att materialet i lagret är för mjukt för att en bra presspassning i sätet ska kunna säkras.

En robot som innefattar led / leder med glapp klarar inte en jämn gång utan störs i sin rörelse eftersom lederna kärvar och rörelserna blir oprecisa. Momentjämvikten i konstruktionen störs, vilket sänker robotens livslängd drastiskt. Slagtiderna förlängs och roboten klarar inte prestandakraven.

Vid drift av deltarobotar uppkommer därmed behovet av att fixera ett lager i ett säte i ledskålen. Detta behov kan inte deltaroboten i den amerikanska patentskriften uppfylla.

REDOGÖRELSE FÖR UPPFINNINGEN

- 5 Vid konstruktion av deltaroboter är syftet enligt uppfinningen att åstadkomma konstruktioner med låg vikt vilka klarar slagtider på 0.5 sekunder. För att uppnå så snabba robotar måste lederna utformas så att friktionen är minimerad.

- 10 Ett visst slitage av ett lager i en led är ofrånkomligt. Ett jämnt slitage av ett självsmörjande lager ger en jämn smörjning av och en jämn rörelse i leden. Vid ett jämnt slitage uppstår inga oönskade glapp och roboten får en jämn och snabb gång.

- 15 Syftet med föreliggande uppfinning är således att åstadkomma en robot innefattande en anordning med vilken man ökar friktionen mellan lager och ledskål i en kula-skål-led. Ett ytterligare syfte med uppfinningen är utforma anordningen så att den möjliggör ett enkelt byte av lager efter behov.

FIGURBESKRIVNING

- 20 Uppfinningen kommer att förklaras närmare genom beskrivning av ett utföringsexempel under hänvisning till bifogade ritning, där

fig 1 visar en ledskål enligt uppfinningen,

- 25 fig 2 visar en ledskål enligt uppfinningen,

fig 3 visar en ledskål enligt uppfinningen anordnad med rillor,

- 30 fig 4 visar en alternativ utformning med skålformat säte och lager,

fig 5 visar en deltarobot.

BESKRIVNING AV UTFÖRINGSEXEMPEL

- 35 En treaxlig kula-skål-led i en robot (fig 5) utgörs av en ledskål och en ledkula. Ledskålen (1) omsluter ledkulan (inte visad) med ett utrymme som utgör en halv sfär eller mindre (fig 1). I ledskålen (1) är ett säte (2) utformat för att hysa ett lager (3). Bestämningen lager avser här endera en lagerring, flera lagerringar eller lagret uppdelat i
- 40 sektioner på något för behovet lämpligtvis. I det här nedan beskrivna utföringsexemplet utgörs lagret av en lagerring.

- 45 Sätet (2) innefattar en yta (4) mot vilken lagerringen (3) presspassas (fig 2). Lagerringen (3) är tillverkad av ett polymermaterial och presspassas på plats med hjälp av verktyg på sedvanligt sätt. För att öka friktionen mellan ledskålens yta (4) och lagerringen (3) anordnas friktionshöjande organ (5) på ytan (4). De friktionshöjande organen kan utformas såsom exempelvis en vågstruktur i form av rillor (5') (fig 3). Rillorna (5') riktning i längsled bildar vinkeln (α) med lagerringens centrumaxel (A). Rillorna (5') är företrädesvis parallella med centrumaxeln (A). Rillorna bör dessutom ha spetsiga toppar för att säkerställa friktionen. När

lagerringen (3) anordnas i sätet (2) åstadkommer de friktionshöjande organen (5) en plastisk deformation av lagerringen (3) genom att tränga in i dennas material.

- 5 En alternativ utformning av uppfinningen är att göra lagrets mantelyta kompatibel mot de friktionshöjande organen (5) anordnade på ledskålens yta (4). I den ovan beskrivna utföringsformen med friktionshöjande organ (5) i form av rillor (5') kan lagret (3) därmed alternativt utformas med till sätets yta kompatibla rillor.

- 10 En ytterligare alternativ utformning av uppfinningen är att utforma ledskålens säte skålformat och försett med rillor. Lagret utformas då med en skålformad ytteryta och placeras utan presspassning i ledskålens säte. I den här utformningen av uppfinningen är det den fjäderkraft som håller ihop kula-skål-leden som även fixerar lagret.

PATENTKRAV

- 1 Robot innefattande minst en länkanordning i vilken stag är anordnade i
5 flerledssystem där lederna innefattar treaxliga kula-skål-leder
k ä n n e t e c k n a d a v att ett lager (3) är fixerat mot rotation i ett säte (2) i
en leds ledskål (1), vilket säte (2) innefattar en yta (4) mot vilken lagret (3)
anligger och att ytan (4) är utformad med friktionshöjande organ (5).
- 10 2 Anordning enligt patentkrav 1 k ä n n e t e c k n a d a v att lagret (3) utgörs av
en lagerring (3').
- 15 3 Anordning enligt patentkrav 1-2 k ä n n e t e c k n a d a v att de
friktionshöjande organen (5) genom en plastisk deformation av lagret (3)
intränger i dennas material.
- 20 4 Anordning enligt patentkrav 1-3 k ä n n e t e c k n a d a v att de
friktionshöjande organen (5) är utformade i form av rillor (5').
- 5 Anordning enligt något av patentkraven 1-4 k ä n n e t e c k n a d a v att lagret
25 (3) anligger med presspassning mot ytan (4).
- 6 Anordning enligt patentkrav 4 k ä n n e t e c k n a d a v att rillorna (5') är
30 riktade huvudsakligen parallellt med lagrets centrumaxel (A).
- 7 Anordning enligt patentkraven 1-6 k ä n n e t e c k n a d a v att lagret är
tillverkad av ett polymermaterial.
- 35 8 Anordning enligt något av patentkraven 1-7 k ä n n e t e c k n a d a v att
roboten är en deltarobot.
- 40 9 Förfarande för att i en robot innefattande minst en länkanordning i vilken stag är
anordnade i flerledssystem, vilka leder innefattar treaxliga kula-skål-leder och
där en leds ledskål (1) bringas att innefatta ett säte (2) för att mottaga ett lager
45 (3), vilket säte (2) bibringas en yta (4) mot vilken lagret anligger
k ä n n e t e c k n a t a v att lagret (3) fixeras mot rotation i sätet (2) genom att
ytan (3) förses med friktionshöjande organ (5) vilka bringas i grepp med lagret
(3) när lagret (3) inpassas på plats.

10 Förfarande enligt patentkrav 9 k ä n n e t e c k n a t a v att lagret (3)
presspassas på plats i ledskålens (1) säte (2).

5 11 Förfarande enligt patentkrav 9 k ä n n e t e c k n a t a v att de friktionshöjande
organen (5) plastiskt deformerar lagrets material när lagret (4) passas på plats.

10 12 Användning av en anordning enligt krav 1 och ett förfarande enligt krav 9 för
fixering av ett lager i en robot innefattande minst en länkanordning i vilken stag
är anordnade i flerledssystem där lederna innefattar treaxliga kula-skål-leder.

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SAMMANFATTNING

15 Anordning för fixering av ett lager i en treaxlig kula-skål-led anordnad i en robot. Lagret är anordnat i ett säte (2) på ledskålen (1) och sätet (2) innefattar en yta (3) mot vilken lagret anligger . Ytan (3) är utformad med friktionshöjande organ (4) vilka greppar tag i lagret och håller fast det.

20 (fig 1)

PATENT COOPERATION TREATY

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International application No.

PCT/SE99/02255

International filing date
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02-12-1999

Applicant
ABB AB
et al

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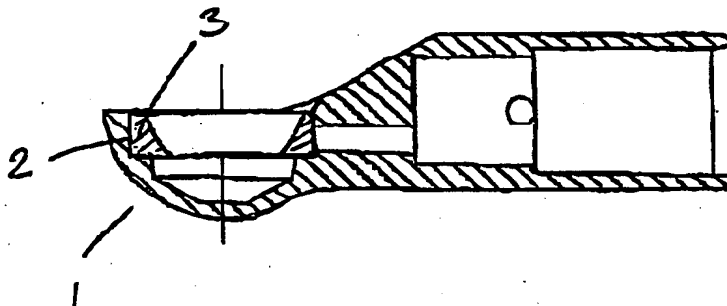
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(21) International Application Number: PCT/SE99/02255 (22) International Filing Date: 2 December 1999 (02.12.99) (30) Priority Data: 9804215-3 3 December 1998 (03.12.98) SE (71) Applicant (for all designated States except US): ABB AB [SE/SE]; S-721 83 Västerås (SE). (72) Inventors; and (75) Inventors/Applicants (for US only): PERSSON, Fredrik [SE/SE]; Markörgatan 10 A, S-723 38 Västerås (SE). MIKAELSSON, Pierre [SE/SE]; Haga Parkgatan 3D, S-723 36 Västerås (SE). HVIITTFELDT, Håkan [SE/SE]; Brunnbygatan 64, S-722 23 Västerås (SE). LARSSON, Jön [SE/SE]; Adolf Zethelius gata 11, S-724 78 Västerås (SE). (74) Agents: URBAN, Petré et al.; AB Stockholms Patentbyrå, Zacco & Bruhn, P.O. Box 23101, S-104 35 Stockholm (SE).		(81) Designated States: AE, AL, AM, AT, AT (Utility model), AU, A7, RA, BB, BG, BR, BY, CA, CH, CN, CR, CU, CZ, CZ (Utility model), DE, DE (Utility model), DK, DK (Utility model), DM, EE, EE (Utility model), ES, FI, FI (Utility model), GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SK (Utility model), SL, TJ, TM, TR, TT, TZ, UA, UG, US, UZ, VN, YU, ZA, ZW, ARIPO patent (GH, GM, KE, LS, MW, SD, SL, SZ, TZ, UG, ZW), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, CY, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), UAPI patent (BF, DJ, CF, CG, CI, CM, GA, GN, GW, ML, MR, NE, SN, TD, TG). Published <i>With international search report.</i> <i>Before the expiration of the time limit for amending the</i> <i>claims and to be republished in the event of the receipt of</i> <i>amendments.</i> <i>In English translation (filed in Swedish).</i>

(54) Title: ROBOT DEVICE**(57) Abstract**

Device for fixing a bearing means firmly in a three-axis ball and socket joint arranged in a robot. The bearing means is arranged in a housing (2) on the joint socket (1) and the housing (2) includes surface (4) against which the bearing means abuts. Surface (4) is designed with friction-increasing means (5) that grip the bearing means and hold it.

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WO 00/32363

2/PRTS

09/857348
JC Rec'd PCT/PTO 04 JUN 2001
PCT/SE99/02255ROBOT DEVICE

5 TECHNICAL FIELD

The present invention relates to a device, use and method to eliminate the risk of play in a three-axle joint in a robot.

10 PRIOR ART

In a delta robot, a positioning of a moveable element in relation to a fixed element takes place (Fig. 5). Three driving means each drive their own link device arranged between the fixed and the moveable elements. The link devices can include rods arranged in multi-joint systems where the joints can comprise ball and socket joints.

The American document US,A, 4 976 582 shows, among other things, a delta robot with two parallel links 5a and 5b joined to pivot with ball and socket joints 26a, 26b, 27a, and 27b (Fig. 5). The joint sockets are attached to the ends of the links.

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The ball and socket joints according to the invention are designed with replaceable bearing means that minimise friction in the joints. The bearing means has a socket-shaped inner surface and is manufactured in self-lubricating polymer material. The bearing means is arranged in a seat in the joint socket. During the operation of the robot, rotational movements take place in the ball and socket joints and directional movements also occur.

25

Problems arise when the bearing means follows the rotational movement, i.e. follows the rotation movement of the ball of the joint. In this situation, link movements take place at the same radii take place at the joint socket at each stroke of the linkage device, whereby wear occurs repeatedly at the same location. An uneven wear occurs in the joint, which causes play in the joint and thus increased friction in the joint. The reason that the bearing

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means rotates with the ball joint is that the material in the bearing means is too soft to ensure a good tight fit in the seat.

5 A robot including a joint / joints with play does not work at a smooth pace but is disturbed in its movement as the joints bind and the movements become imprecise. The balance of moments in the construction is disturbed, which drastically reduces the working life of the robot. The cycle time increases and the robot cannot meet its performance requirements.

10 In the operation of robots, the need thus arises to firmly fix a bearing means in a seat in a joint socket. This need cannot be met by the delta robot in the American document.

SUMMARY OF THE INVENTION

15 When designing delta robots, the objective according to the invention is to achieve a design with a low weight that can handle a stroke time of 0.5 seconds. To achieve robots that are this fast, the joint must be designed so that friction is minimised.

20 A certain wear on the bearing means in a joint is unavoidable. An even wear of a self-lubricating bearing means gives an even lubrication of and a smooth movement in the joint. When the wear is even, no unwanted play occurs and the robot has a smooth, rapid operation.

25 The object of the present invention is thus to achieve a robot including a means with which one increases the friction between bearing means and socket in a ball and socket joint. An additional object of the invention is to design the device so that it allows an easy replacement of bearing means according to need.

DESCRIPTION OF THE DRAWING

30 The invention will be explained in greater detail by describing an example of an embodiment with reference to the enclosed drawings, where;

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Fig. 1 shows a socket of a joint according to the invention.

Fig. 2 shows a joint socket according to the invention,

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Fig. 3 shows a joint socket according to the invention arranged with grooves,

Fig. 4 shows an alternative design with a socket-shaped seat and bearing means,

10 Fig. 5 shows a delta robot.

DESCRIPTION OF EMBODIMENTS

A three axle ball and socket joint in a robot (Fig. 5) comprises a joint socket and a joint
15 ball. The joint socket 1 encloses the ball of the joint (not shown) with a space that
comprises approximately a half of a sphere or less (Fig. 1). A housing 2 shaped to
accommodate a bearing means 3 is located within socket 1.

The word bearing here relates to either one annular bearing, several annular bearings or
the bearing divided into sections in a way suitable for the purpose. In the embodiment
20 described below, the bearing means comprises one annular bearing means.

The housing 2 includes a surface 4 against which the annular bearing means 3 is pressed to
fit tightly (Fig. 2). Annular bearing means 3 is manufactured from a polymer material and
is pressed to fit tightly in place with the aid of a tool in the traditional manner. To increase
25 the friction between surface 4 of the joint socket and the annular bearing means 3, friction-
increasing means 5 are arranged on the surface 4. The friction-increasing means can be
designed as, for example, a wave structure in the form of grooves 5' (Fig. 3). The
orientation of the grooves 5' in a longitudinal direction forms the angle (α) with the centre
axis (A) of the annular bearing means. Grooves 5' are preferably parallel with the centre
30 axis (A). In addition, the grooves should have sharply pointed tops to secure the friction.
When the annular bearing means 3 is arranged in the housing 2, the friction-increasing

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means 5 achieve a permanent deformation of the annular bearing means 3 by penetrating its material.

- An alternative design of the invention is to make the envelope surface of the bearing
- 5 means compatible to the friction-increasing means 5 arranged on the surface of the joint socket 4. In the embodiment described above with the friction-increasing means 5 in the form of grooves 5', the bearing means 3 can thus be alternatively designed with grooves that are compatible with the surface of the housing.
- 10 A further alternative design of the invention is to design the housing of the joint socket socket-shaped and provided with grooves. Then the bearing means is designed with a socket-shaped outer surface and is placed without being pressed to fit tightly in the housing of the joint socket. In this design of the invention, it is the spring force that holds the ball and socket joint together that also fixes the bearing means firmly in place.

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CLAIMS

1. Robot including at least one linkage device in which pull rods are arranged in a multi-joint system where the joints include three-axle ball and socket joints
characterised in that a bearing means (3) is fixed so that it does not rotate in a
5 housing (2) in the socket of a joint (1), where housing (2) includes a surface (4) against
which the bearing means (3) abuts and that the surface (4) is designed with friction-
increasing means (5).
2. Device according to claim 1 characterised in that the bearing means (3)
10 comprises an annular bearing means (3').
3. Device according to claims 1-2 characterised in that the friction-increasing
means (5) penetrate its material by a permanent deformation of the bearing means (3).
- 15 4. Device according to claims 1-3 characterised in that the friction-increasing
means (5) are designed in the form of grooves (5').
5. Device according to claims 1-4 characterised in that bearing means (3) abuts
with surface (4) and is pressed to fit tightly.
20
6. Device according to claim 4 characterised in that grooves (5') are oriented
primarily parallel with the central axis (A) of the bearing means.
7. Device according to claims 1-6 characterised in that the bearing means is made
25 of a polymer material.
8. Device according to any of claims 1-7 characterised in that the robot is a delta
robot.
- 30 9. Method for a robot including at least one linkage device in which pull rods are arranged
in a multi-joint system where the joints include three-axle ball and socket joints and
where a socket (1) of a joint is provided with a housing (2) to accommodate a bearing

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means (3), where the housing (2) is provided with a surface (4) against which the bearing means abuts characterised in that bearing means (3) is fixed so that it does not rotate in housing (2) by providing surface (4) with friction-increasing means (5) that are brought to engage with bearing means (3) when bearing means (3) is positioned in place.

10. Method according to claim 9 characterised in that the bearing means (3) is pressed to fit tightly in place in the housing (2) of the joint socket (1).

10 11. Method according to claim 9 characterised in that friction-increasing means (5) deform the material of the bearing means by permanent deformation when bearing means (3) is placed in position.

15 *utgå* ~~12. Use of a device according to claim 1 and a method according to claim 9 for fixing the location of a bearing means in a robot including at least one linkage device in which rods are arranged in a multi-joint system where the joints include three-axle ball and socket joints.~~

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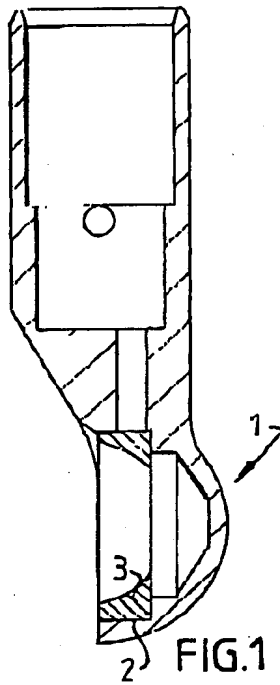


FIG. 1

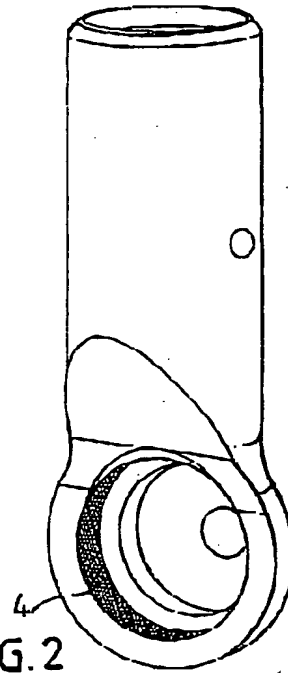


FIG. 2

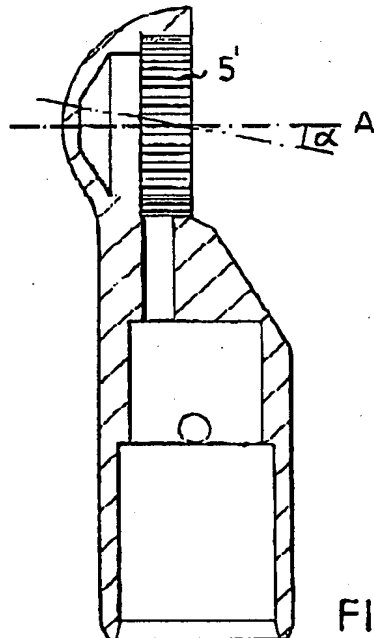


FIG. 3

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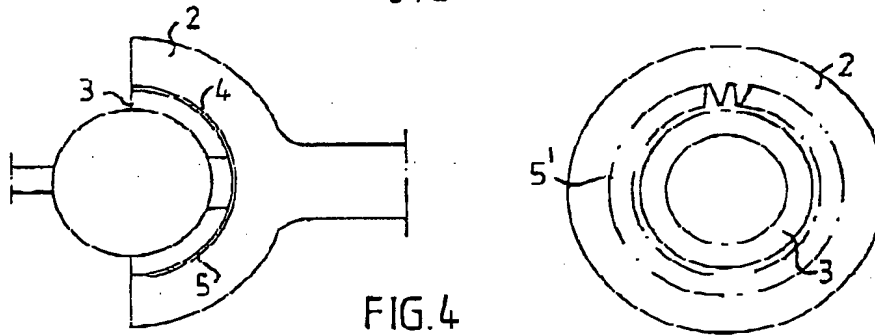


FIG. 4

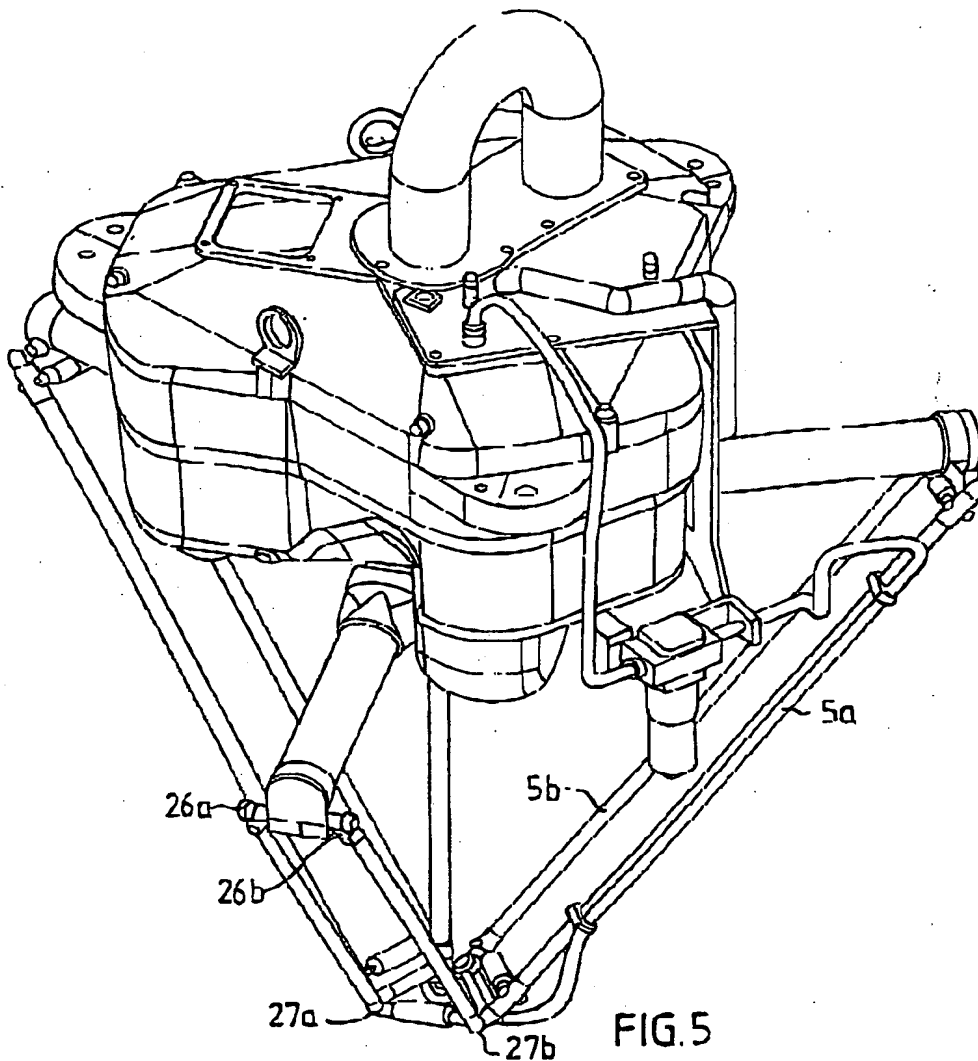


FIG. 5

SUBSTITUTE SHEET (RULE 26)

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INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE 99/02255

A. CLASSIFICATION OF SUBJECT MATTER

IPC7: B25J 17/02, F16C 11/06

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC7: B25J, F16C

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

SE,DK,FI,NO classes as above

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

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Y	US 4695182 A (WOOD, JR.), 22 Sept 1987 (22.09.87), column 5, line 64 - column 6, line 3 --	1-12
Y	EP 0705990 A2 (THK CO. LTD.), 10 April 1996 (10.04.96), column 9, line 44 - line 55 --	1,3-4,9-11
A	US 3856423 A (UCHIDA), 24 December 1974 (24.12.74), column 3, line 66 - column 4, line 6; column 1, line 56 - line 57 --	1,5,7,11

☒ Further documents are listed in the continuation of Box C.☒ See patent family annex.

* Special categories of cited documents

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"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

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Name and mailing address of the ISA
 Swedish Patent Office
 Box 5055, S-102 42 STOCKHOLM
 Facsimile No. +46 8 666 02 86

Authorized officer

Christer Jönsson / MR
 Telephone No. +46 8 782 25 00

INTERNATIONAL SEARCH REPORT

Information on patent family members

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